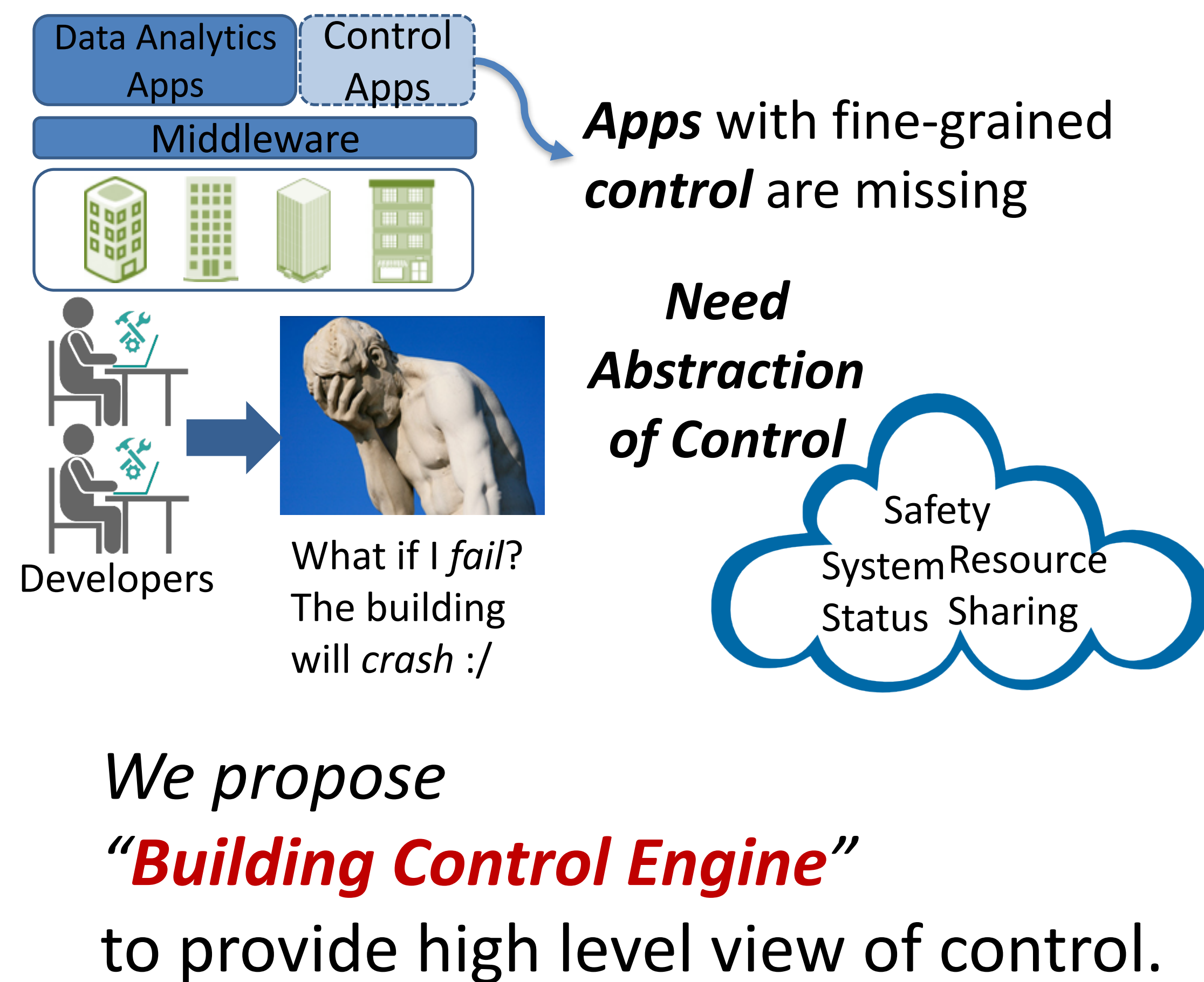


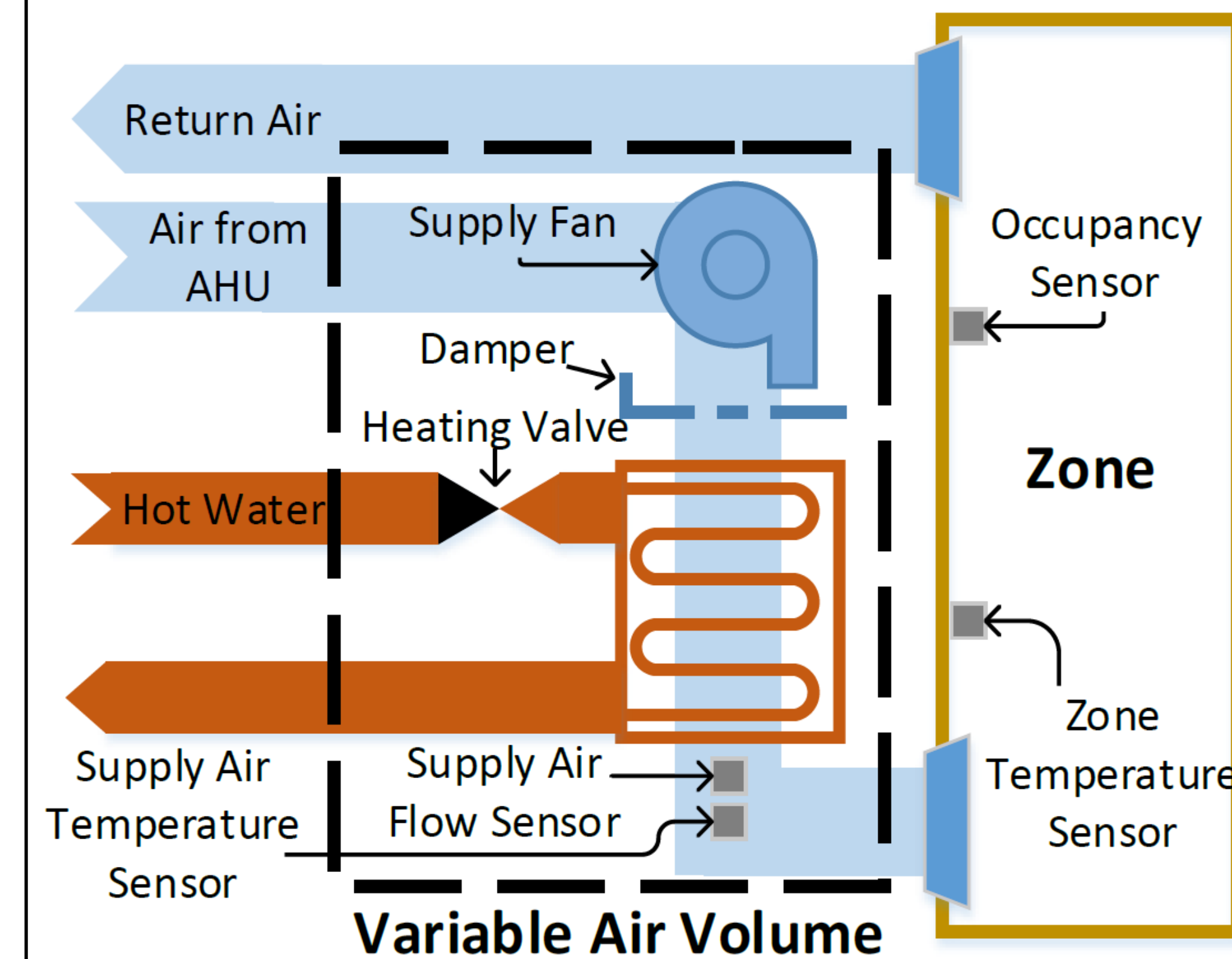
# Controlling Actuation in Central HVAC Systems in Buildings

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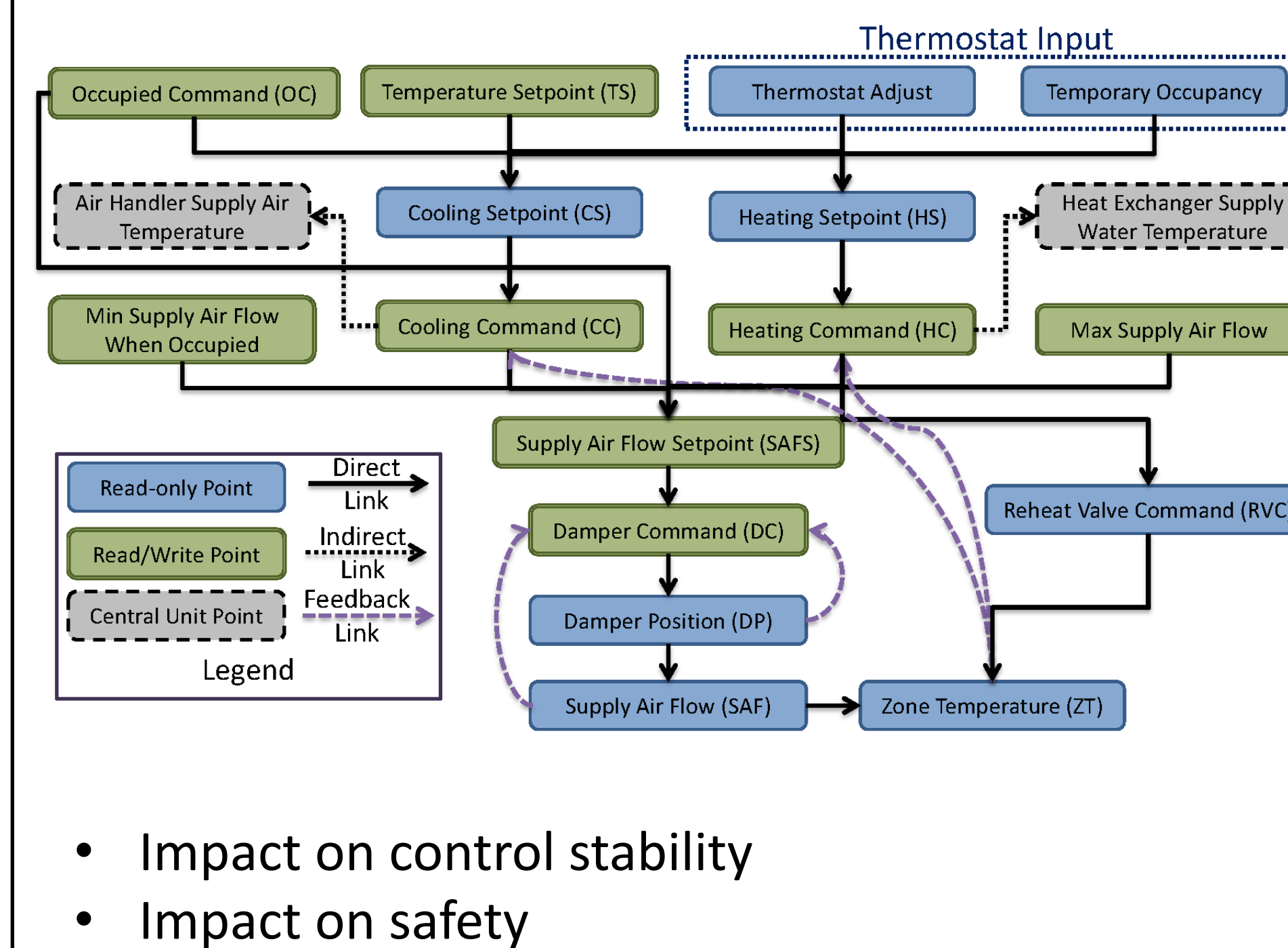
## Need for Control Platform



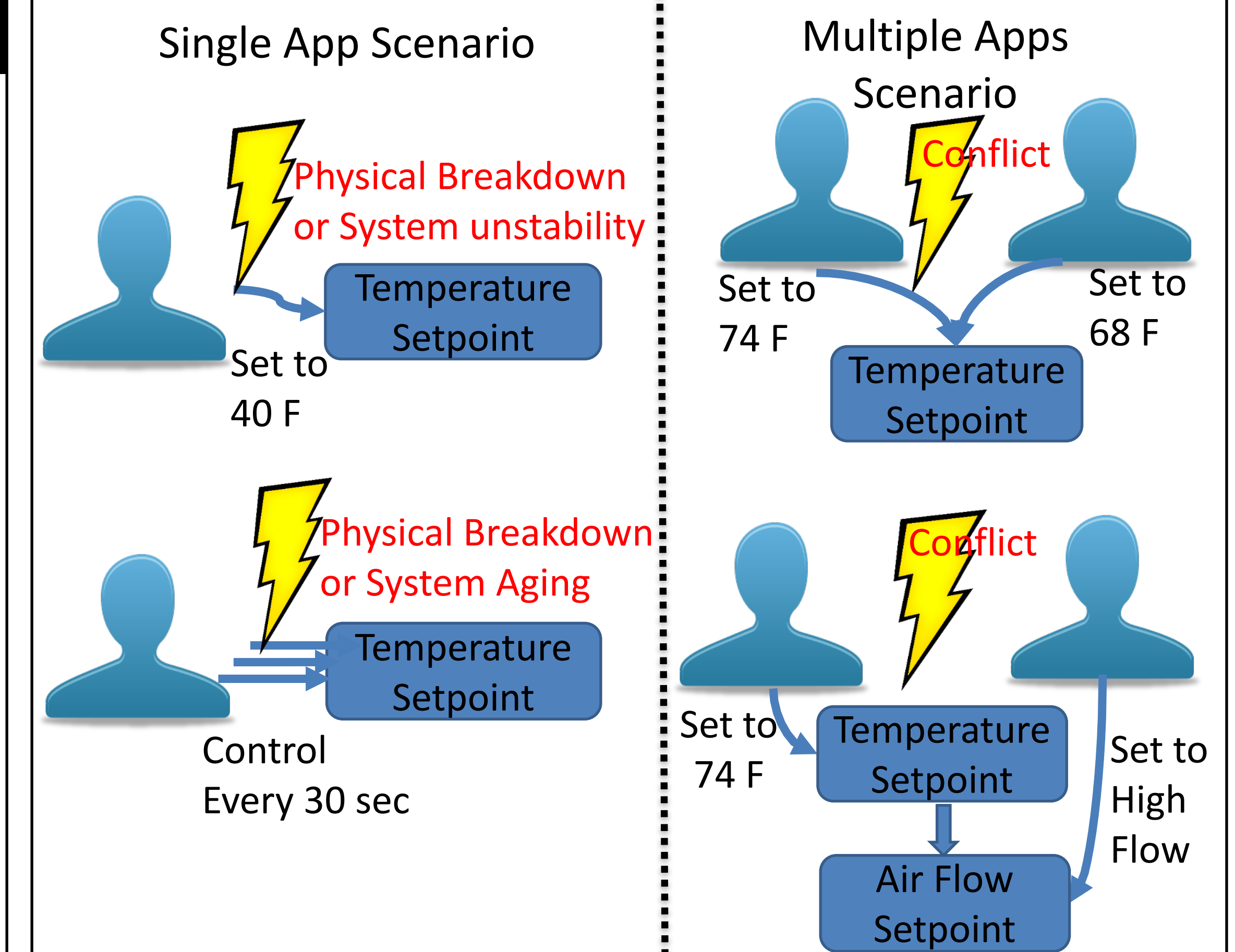
## HVAC Background



## Sensor/Actuator Dependency Graph



## Challenging Scenarios



## Building Control Engine (BCE)

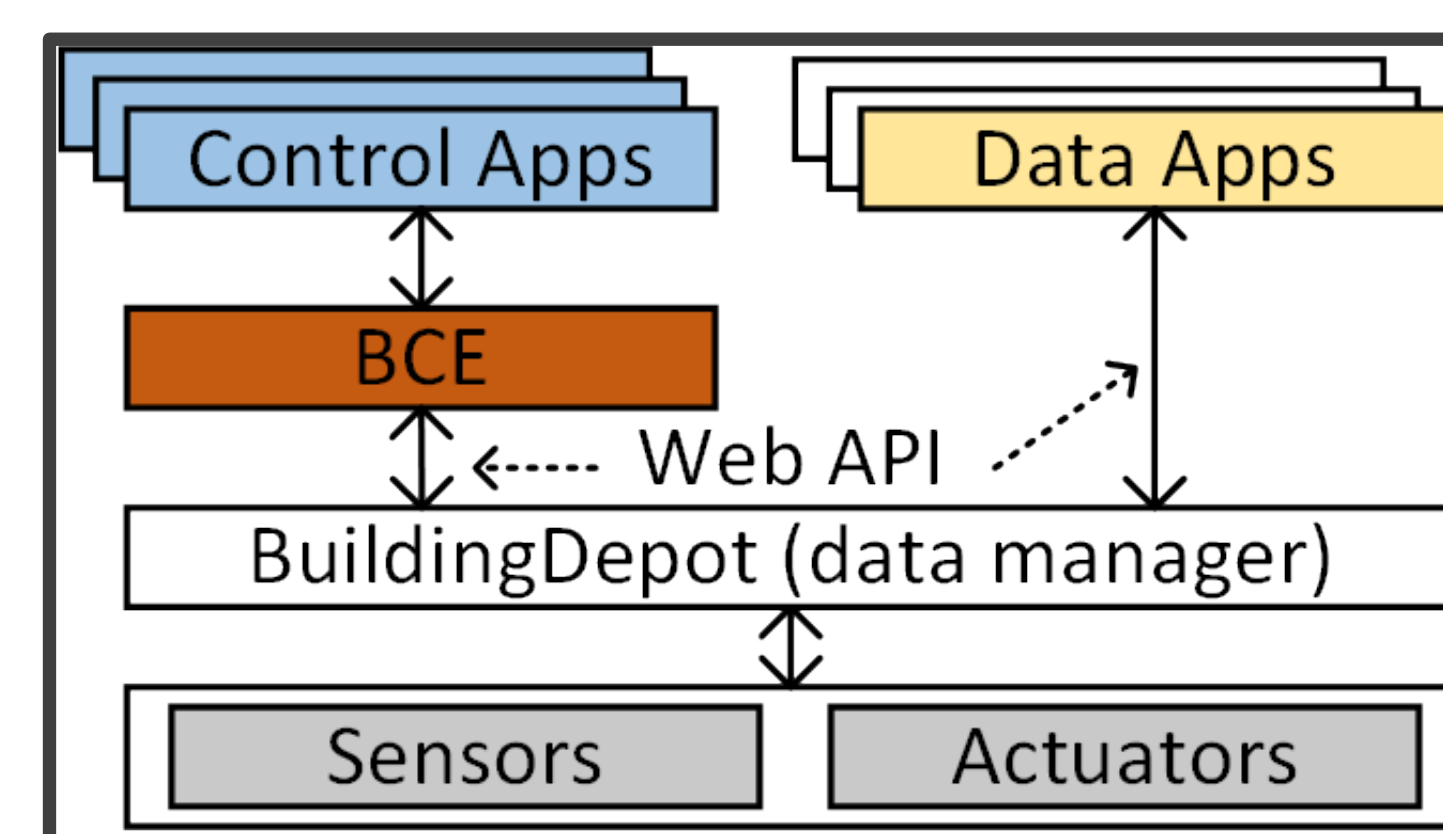
### Design Goal

- 1. Provide a library as API**
- 2. Reject unsafe operation**
  - Should not exceed operating range. e.g., Temperature Setpoint to 40°F
  - Should not operate too frequently. e.g., Damper command change in every 30 seconds.
- 3. Status of operation per a sensor/actuator is stored/managed**
  - Points are dependent on others.
  - Need to track status of each resource, and its dependency information.
- 4. Logging entire history of control**
  - Logging history of all system status
  - Need for both data analysis and system management
- 4. Rollback**
  - In case of system down or user interrupt.

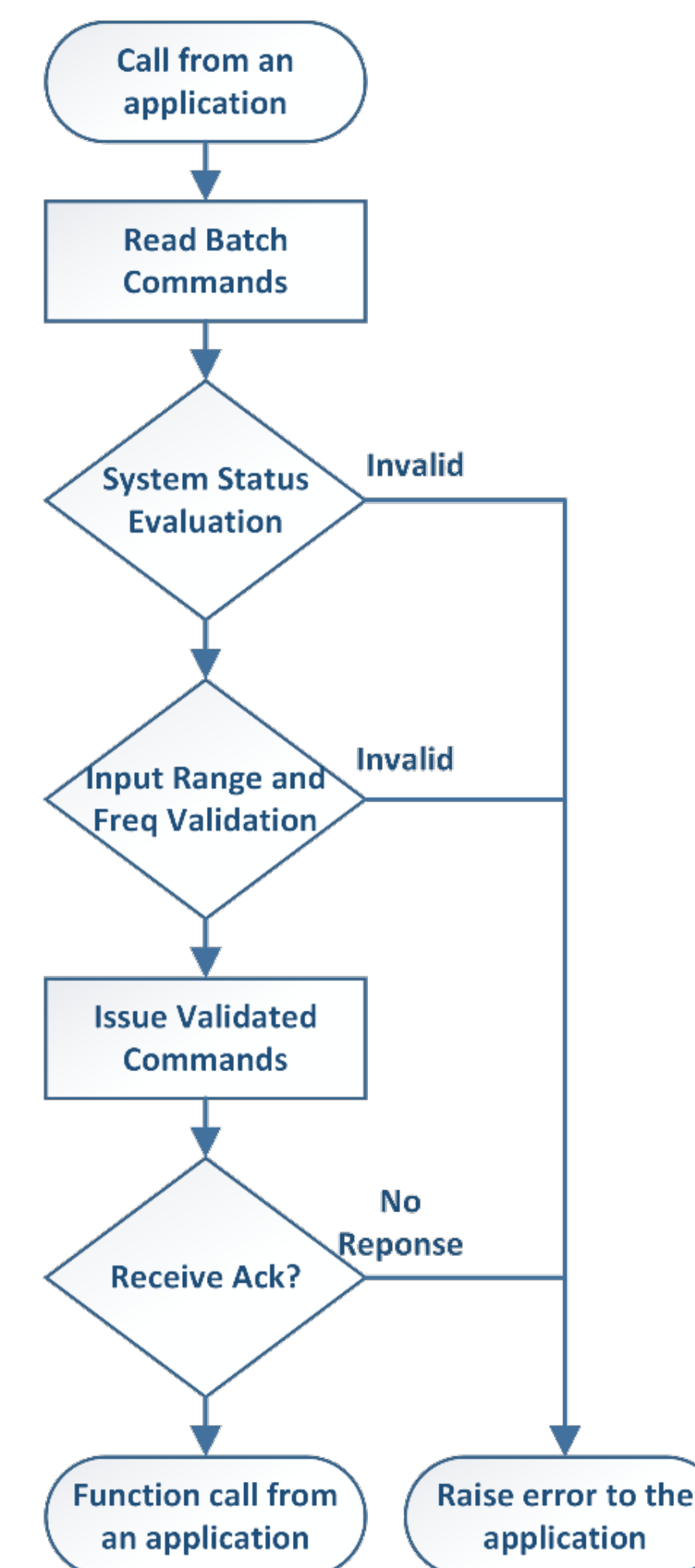
### Unsafe operation

- Definition of unsafe operation
  - Exceeding normal operating range.
  - Too frequent operation.
- Each actuator has its own definition of unsafety.
- Each operation affects dependent points.

### System Architecture



### Validation Algorithm



### Application Suggestion

- 1. System Diagnosis**
  - Active fault diagnosis
  - System estimation for security
- 2. System Identification**
  - Sensor/actuator colocation
  - Type identification
  - Finding control function
  - Finding dependency graph
- 3. Personalized Control**

## Example Application: Sensor/Actuator Co-location

**Problem:** Co-location of sensor/actuators when location metadata is unavailable.  
**Assumption:** Sensor and actuator types are known.

**Hypothesis:** Co-located points will be distinguishable if unique control signal is applied. The signal is unique in terms of *amplitude*, *frequency*, and *phase*.

**Method:** Use control to make information more observable.

### Algorithm for Co-location

Apply large pulses to a Temperature Setpoint

Extract time-series features from each point over all zones

Pick a point with most abnormal features

**Result:** 68 % recall with 98.6 % precision over 8 zones.

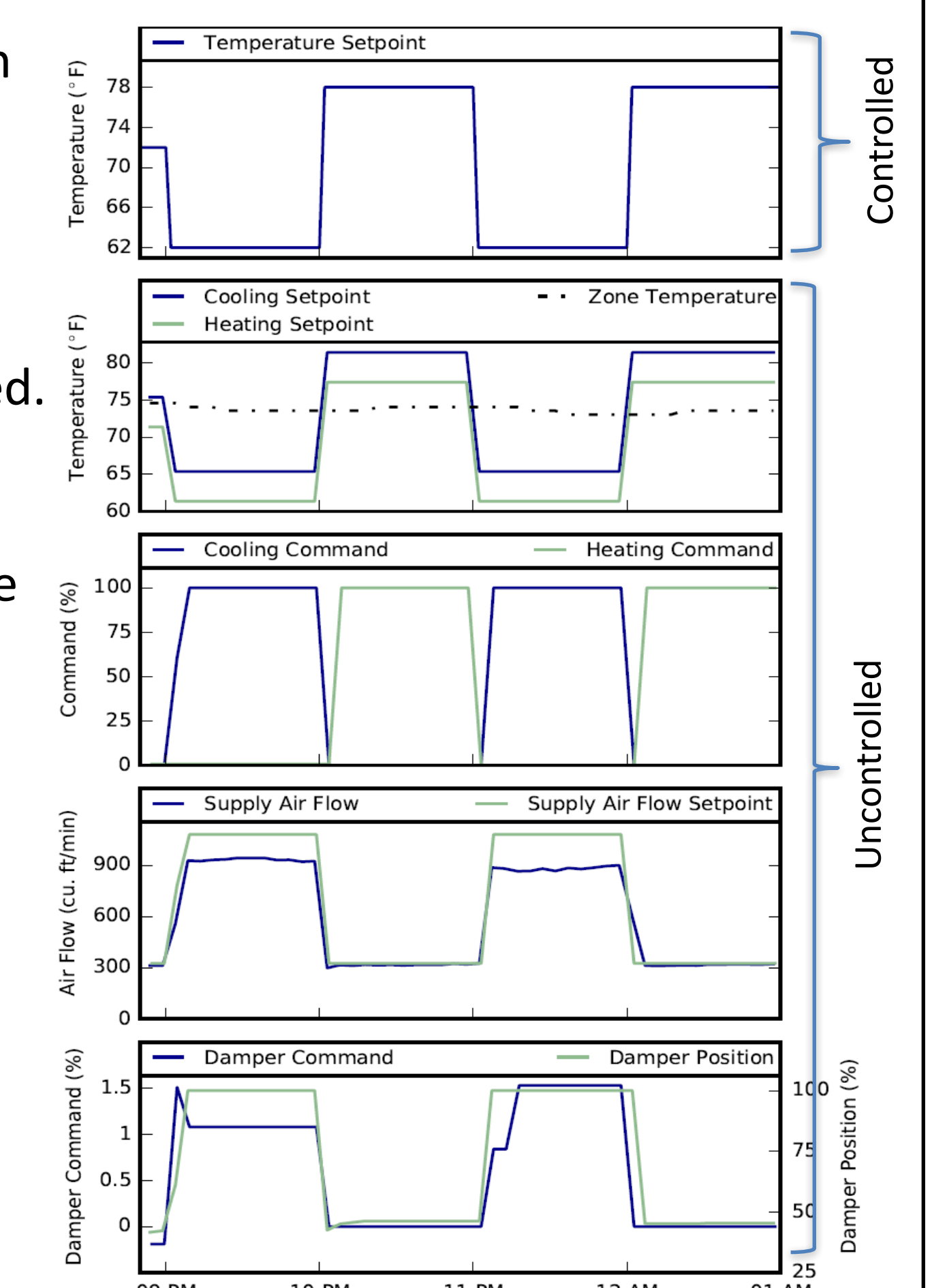


Fig. Example of control experiment for co-location